

# A Roadmap Towards Parallel Printing for Desktop 3D Printers

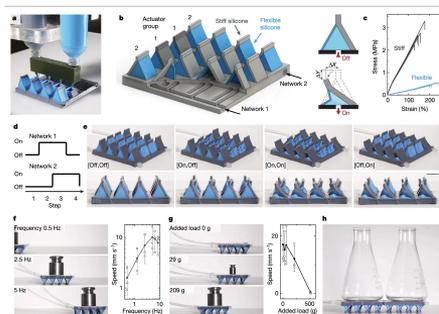


SFF 2021

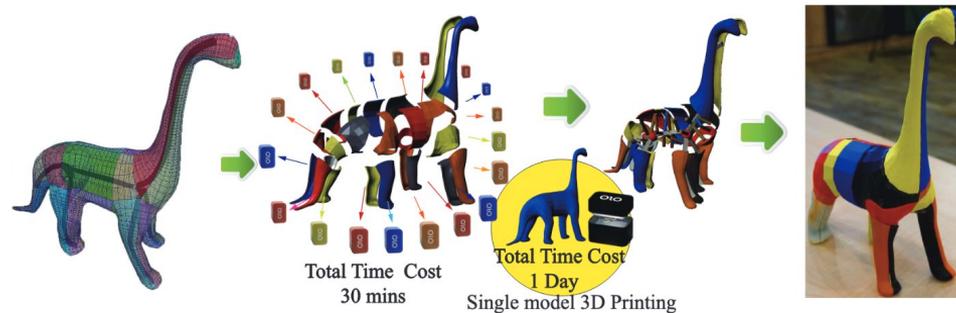


Molly Aubrey Carton, Chandrakana Nandi, Adam Anderson, Haisen Zhao,  
Eva Darulova, Dan Grossman, Jeffrey Ian Lipton, Adriana Schulz, Zachary Tatlock

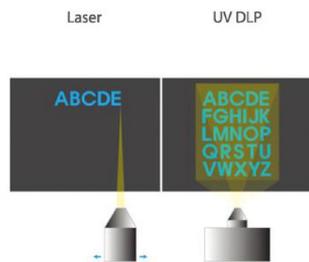
# Existing Parallel 3D Printing



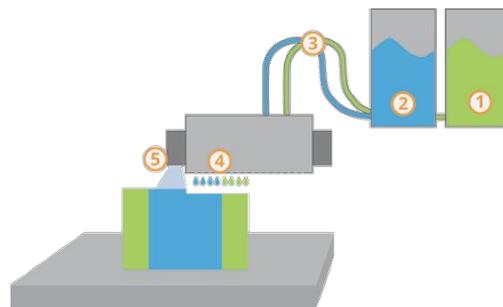
Lewis et al.



Chen et al.



DLP

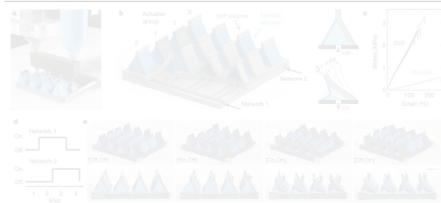


Polyjet

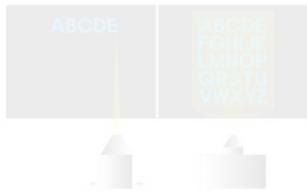


Escher

# Existing Parallel 3D Printing



What about FDM Printers?



DLP



Polyjet



Escher

# Parallel 3D Printing for FDM Printers

Parallel programming: multiple processes speed up compute times



Can we use the extruders simultaneously to print faster by generating parallel toolpaths?

DLP

Polyjet

Escher

# How to Repurpose Existing Tools for Parallel Printing

Hardware

Firmware

G-code Generator

# How to Repurpose Existing Tools for Parallel Printing

Each component affects the others

Hardware

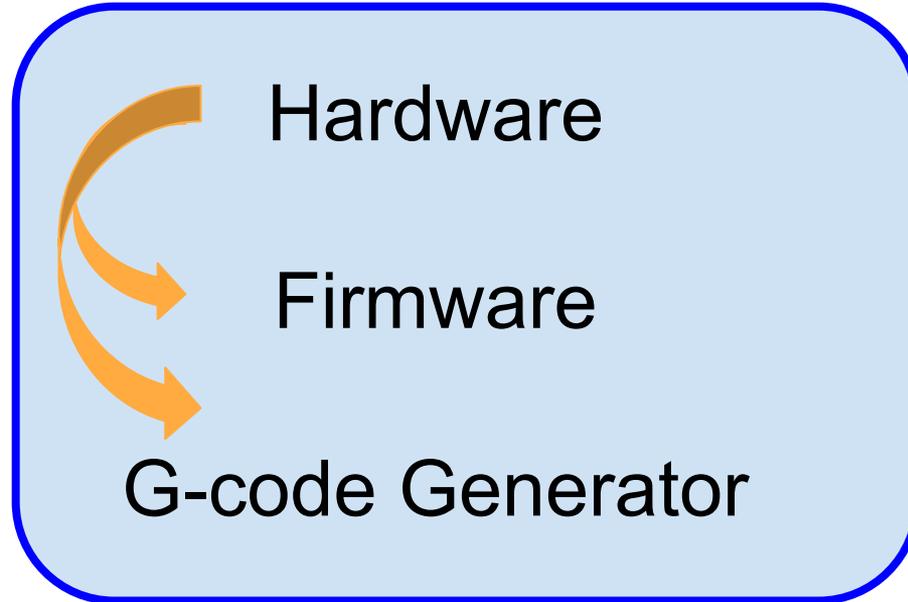
Firmware

G-code Generator

# How to Repurpose Existing Tools for Parallel Printing

Each component affects the others

DOFs

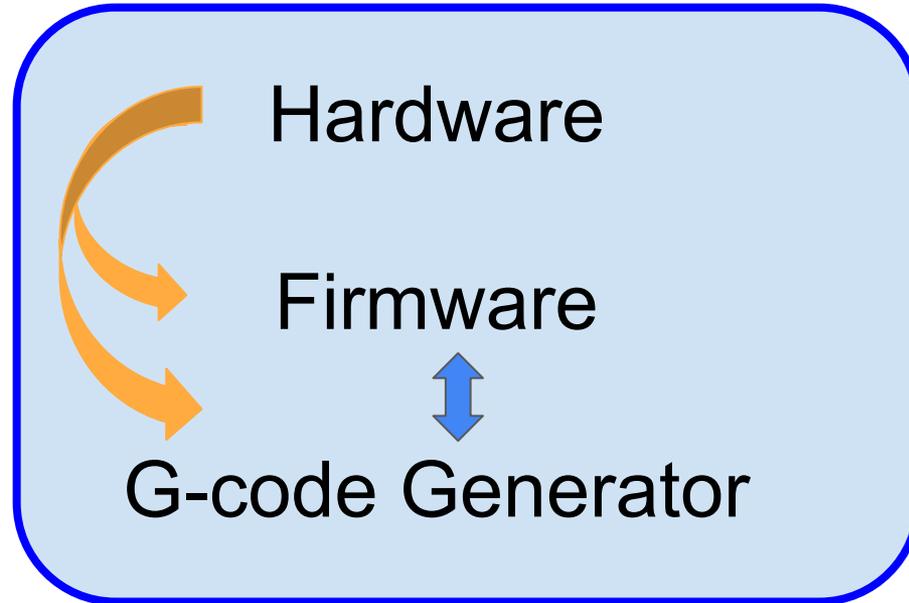


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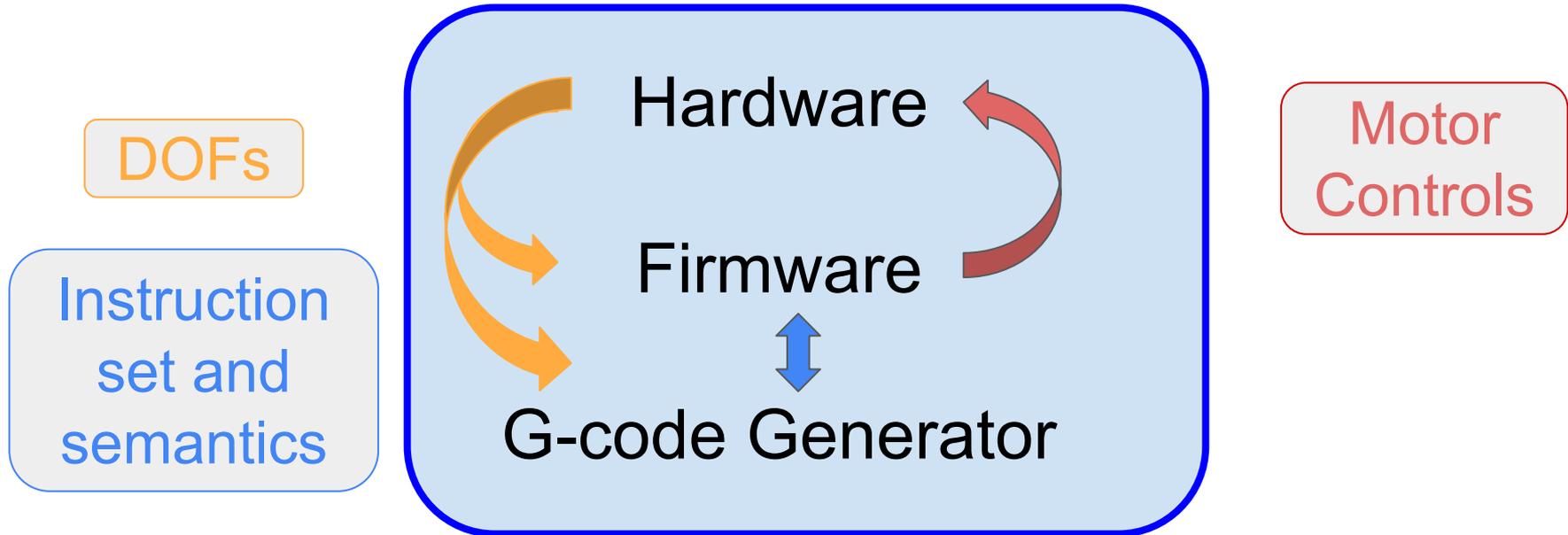
DOFs

Instruction  
set and  
semantics



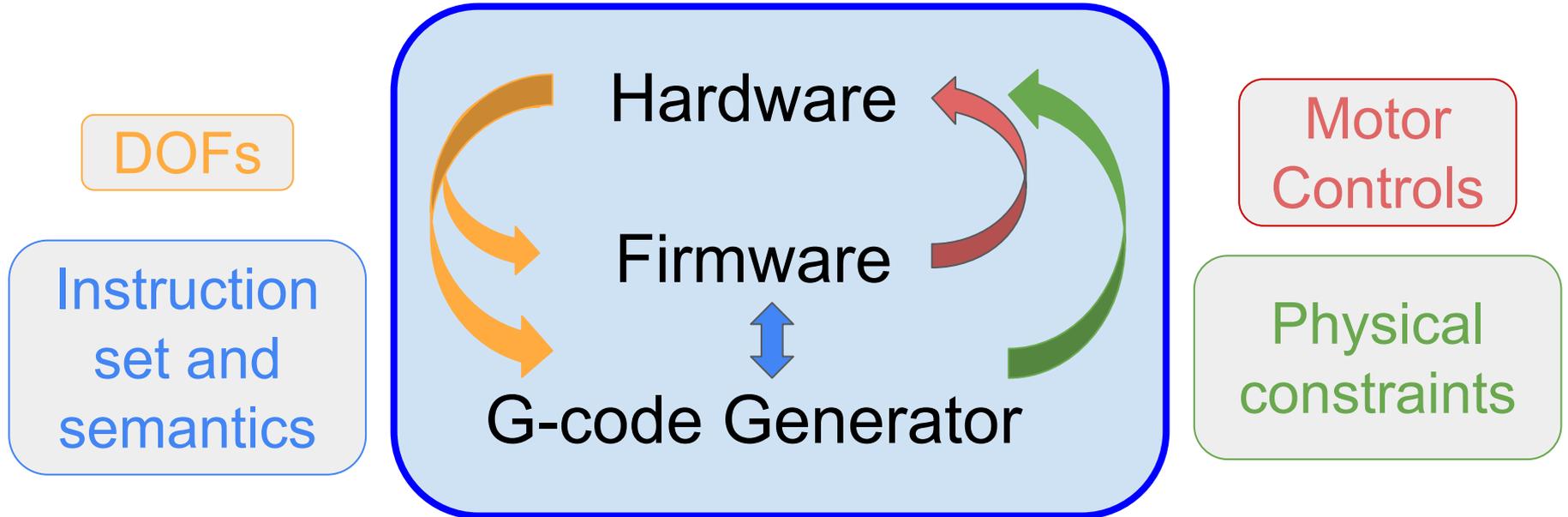
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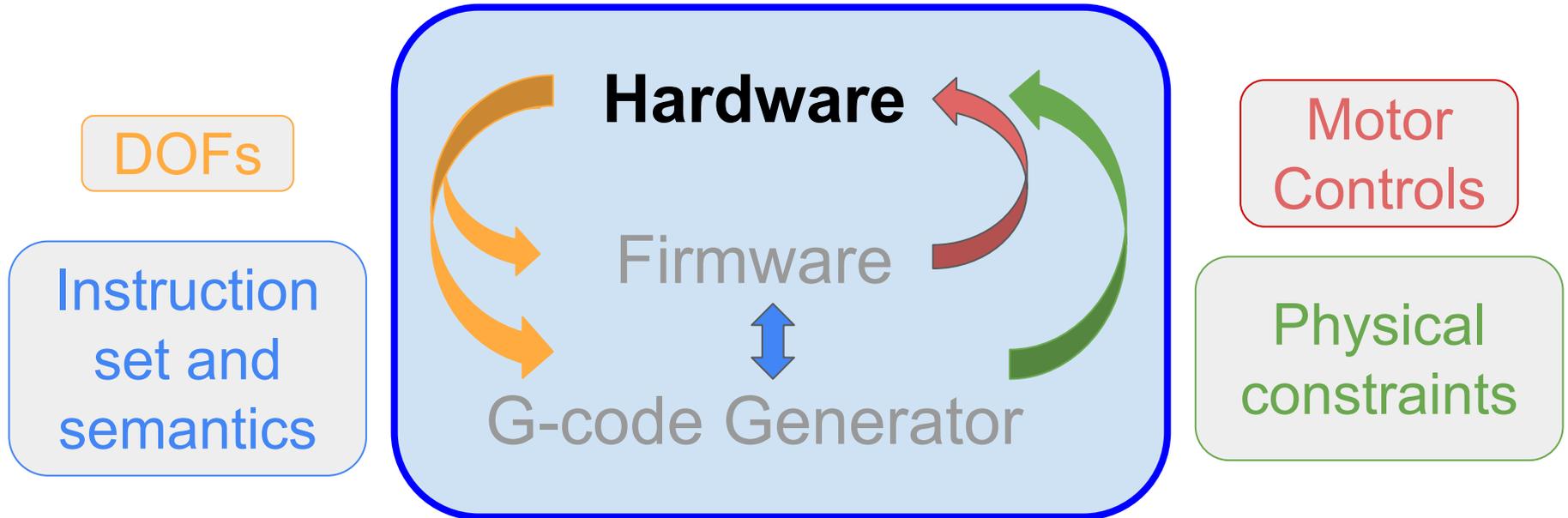
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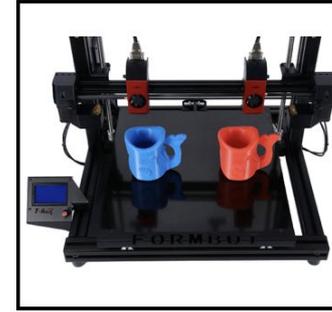
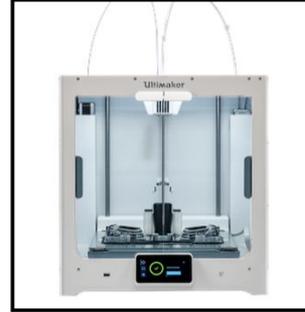
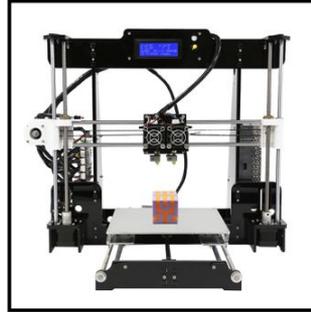
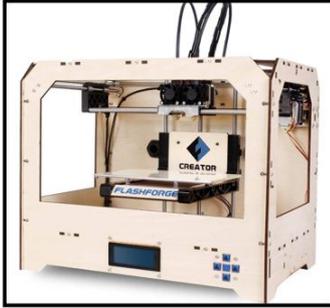


# How to Repurpose Existing Tools for Parallel Printing

Each component affects the others



# FDM 3D Printer Models

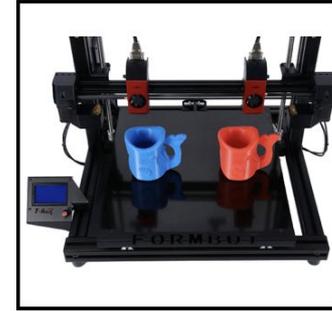
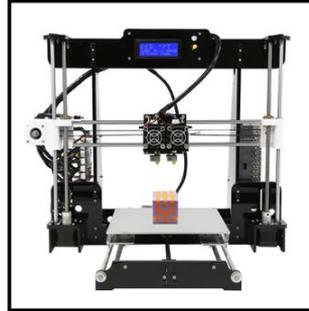
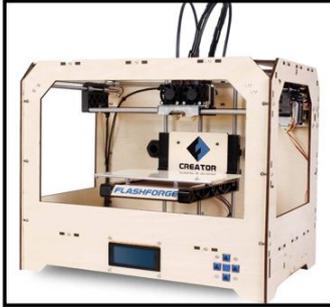


Many FDM 3D printers have multiple extruders!

None use them simultaneously to print the same object

Main uses: ditto printing, multi-color printing, multi-material printing

# FDM 3D Printer Models



- N extruders moving in lockstep
- N extruders with a single independent axis
- N extruders with two independent axes
- N extruders with three independent axes

# FDM 3D Printer Models

Parallelism is restricted / permitted by printer configuration (degrees of freedom)!

- N extruders moving in lockstep
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# FDM 3D Printer Models

Parallelism is restricted / permitted by printer configuration (degrees of freedom)!

- N extruders moving in lockstep
- N extruders with a single independent axis
- N extruders with two independent axes
- N extruders with three independent axes

Fixed-width dual extrusion printers are the most common

# Hardware Support for Parallel Printing

Affordable

Open-source

Ease of experimentation

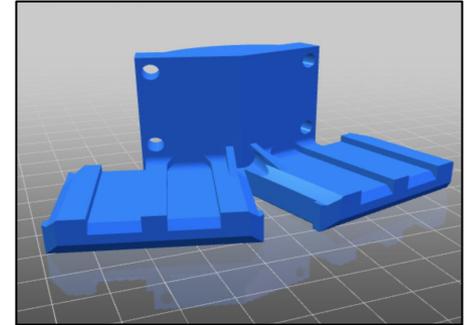
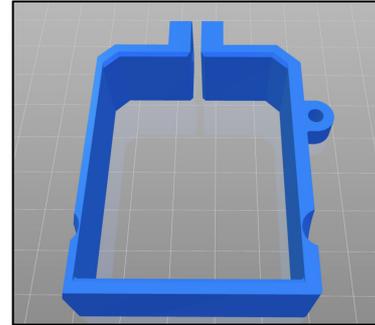
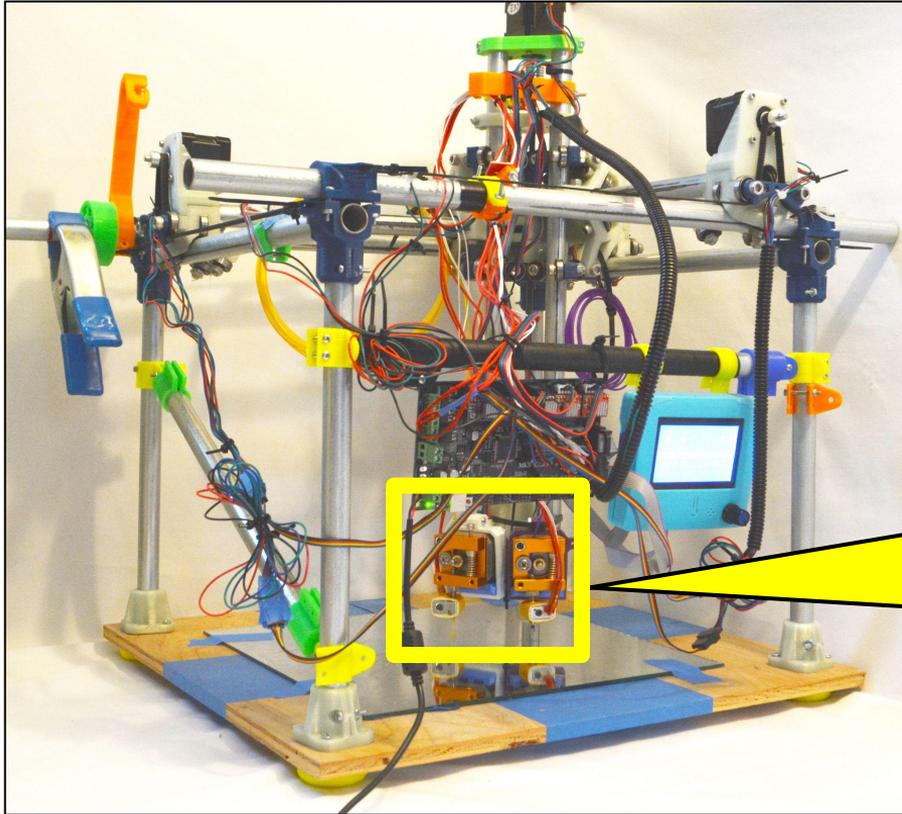
MPCNC 3D Printer

Cheap

Online community

Reconfigurable

# Experimental Hardware: Customized MPCNC 3D Printer

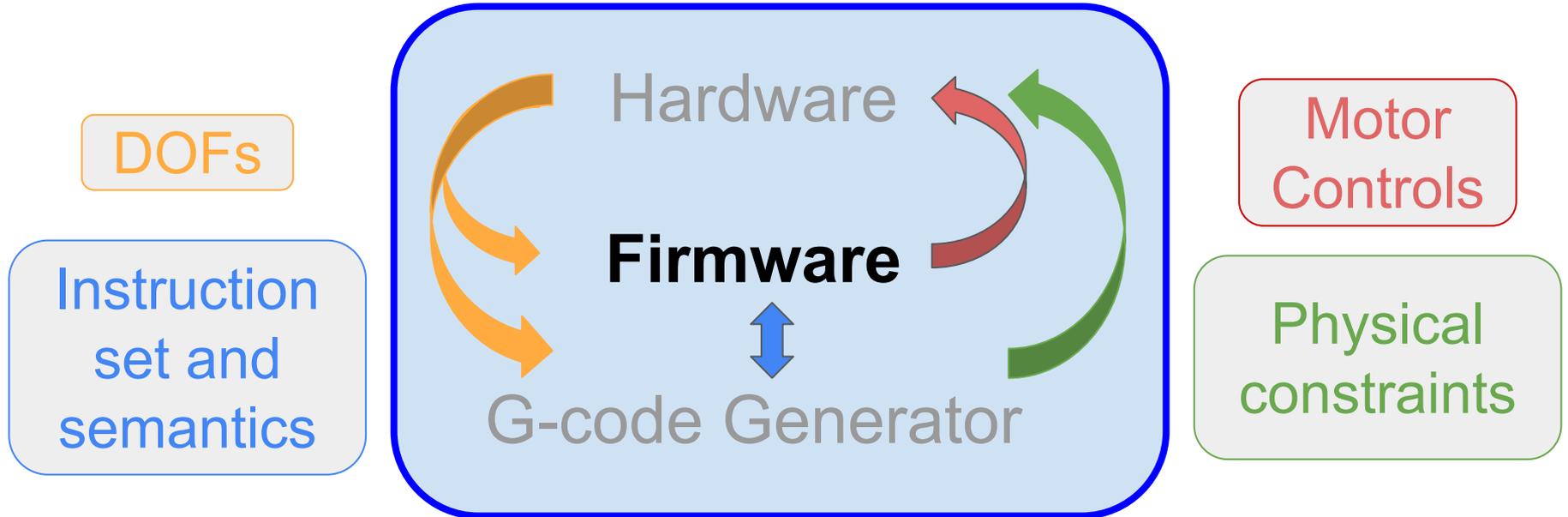


<https://www.thingiverse.com/thing:4883743>

70%, large print area frame  
Fixed-width dual extrusion model  
Custom dual extruder mount

# How to Repurpose Existing Tools for Parallel Printing

Each component affects the others



# Firmware: Interprets G-code

```
G1 X80.000 Y0.80 Z0.00 E2.40
```

Move motor to specified **X**, **Y**, **Z** coordinates while extruding the length of filament provided in the argument to **E**

Typically straight line code interpreted and executed sequentially

How to allow firmware packages to interpret parallel G-code?

# Firmware Support for Parallel Printing

Language support

Extend interpreter

Ease of editability

Marlin firmware

Use the M605 command

Modify the interpreter

Open-source codebase

# Firmware Support for Simultaneous Extrusion

**M605 S2: Dual Nozzle Duplication Mode**

Enable both extruders even when inactive

**M605 S2** toggles extruder duplication

< 20 LOC

# Firmware Support for Simultaneous Extrusion

; Part 1

T1 ; switch to extruder T1

G1 X40.00 Y0.80 Z0.00 E2.40 ; extrude with T1 up to (40.00, 0.80, 0.00)

; Part 2

M605 S2 ; turn on dual extrusion mode

G1 X80.000 Y0.80 Z0.00 E2.40 ; extrude with both up to (80.00, 0.80, 0.00)

M605 S2 ; turn off dual extrusion mode

; Part 3

T0 ; switch to extruder T0

G1 X120.00 Y0.80 Z0.00 E2.40 ; extrude with T0 up to (120.00, 0.80, 0.00)

# Firmware Support for Simultaneous Extrusion

```
; Part 1
```

```
T1 ; switch to extruder T1
```

```
G1 X40.00 Y0.80 Z0.00 E2.40 ; extrude with T1 up to (40.00, 0.80, 0.00)
```

```
; Part 2
```

```
M605 S2 ; turn off
```

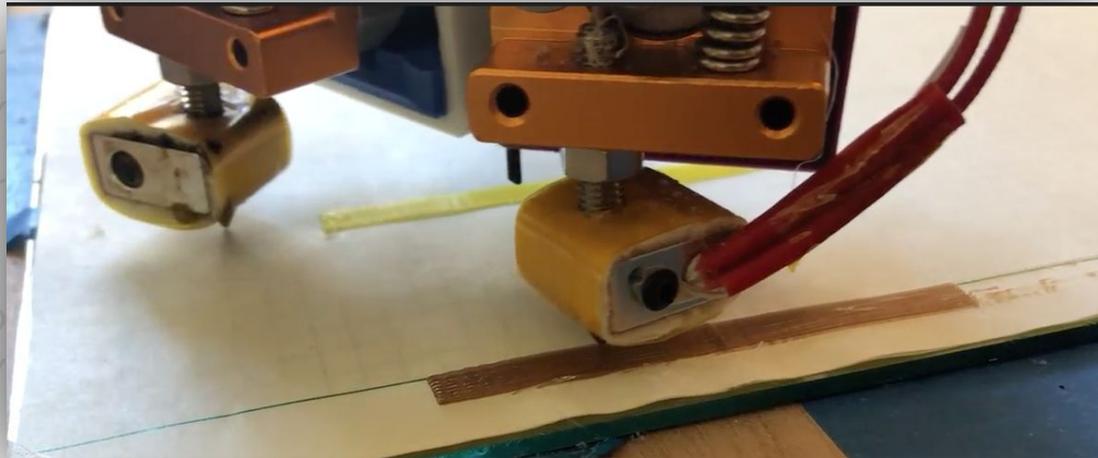
```
G1 X80.000 Y
```

```
M605 S2 ; turn on
```

```
; Part 3
```

```
T0 ; switch to
```

```
G1 X120.00 Y
```



```
(40.00, 0.80, 0.00)
```

```
(40.00, 0.80, 0.00)
```

# Firmware Support for Simultaneous Extrusion



; Part 1

T1 ; switch to extruder

G1 X40.00 Y0.80 Z0.00

(40.00, 0.80, 0.00)

; Part 2

M605 S2 ; turn on dual extrusion mode

G1 X80.000 Y0.80 Z0.00 E2.40 ; extrude with both up to (80.00, 0.80, 0.00)

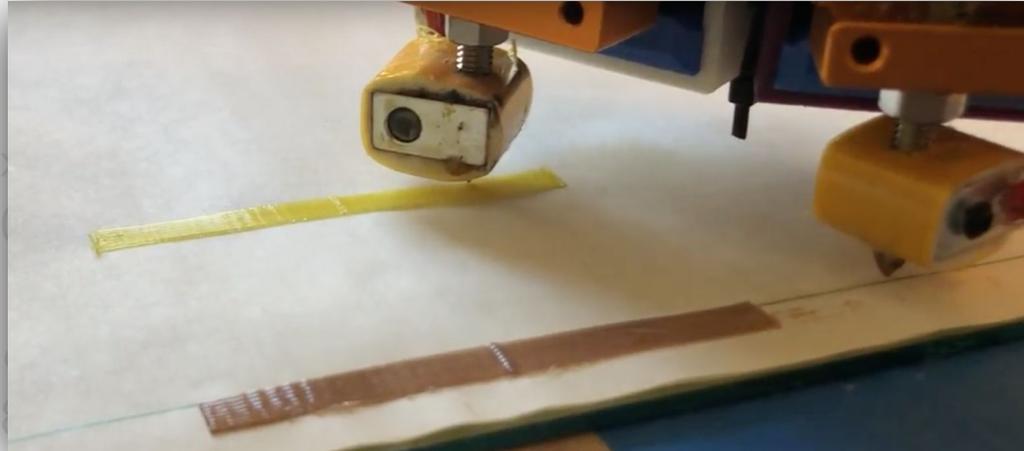
M605 S2 ; turn off dual extrusion mode

; Part 3

T0 ; switch to extruder T0

G1 X120.00 Y0.80 Z0.00 E2.40 ; extrude with T0 up to (120.00, 0.80, 0.00)

# Firmware Support for Simultaneous Extrusion



; Part 1

T1 ; switch to extruder T1

G1 X40.00 Y0.80 Z0.00 E2.40 ; extrude with T1 up to (40.00, 0.80, 0.00)

; Part 2

M605 S2 ; turn on dual extrusion mode

G1 X80.000 Y0.80 Z0.00 E4.80 ; extrude with T1 up to (80.00, 0.80, 0.00)

M605 S2 ; turn off dual extrusion mode

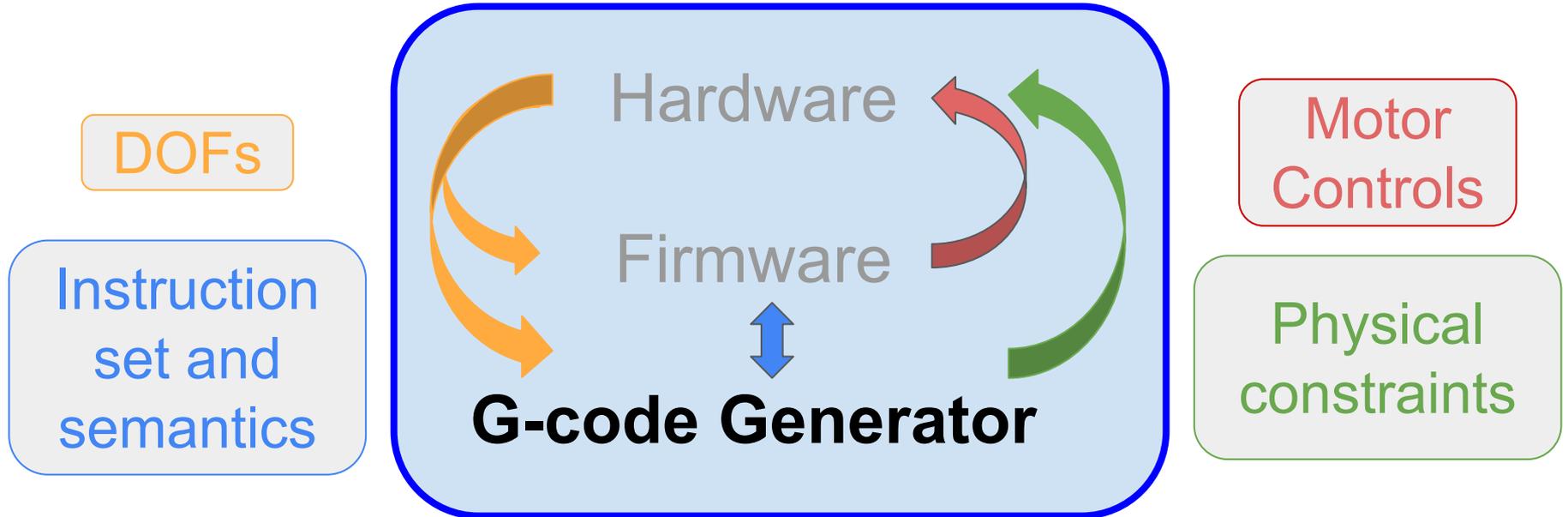
; Part 3

T0 ; switch to extruder T0

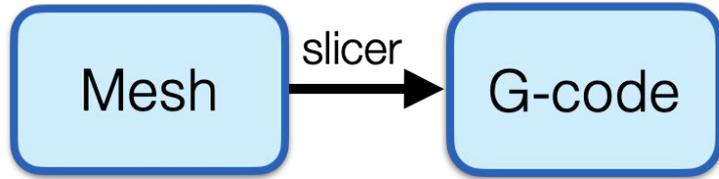
G1 X120.00 Y0.80 Z0.00 E2.40 ; extrude with T0 up to (120.00, 0.80, 0.00)

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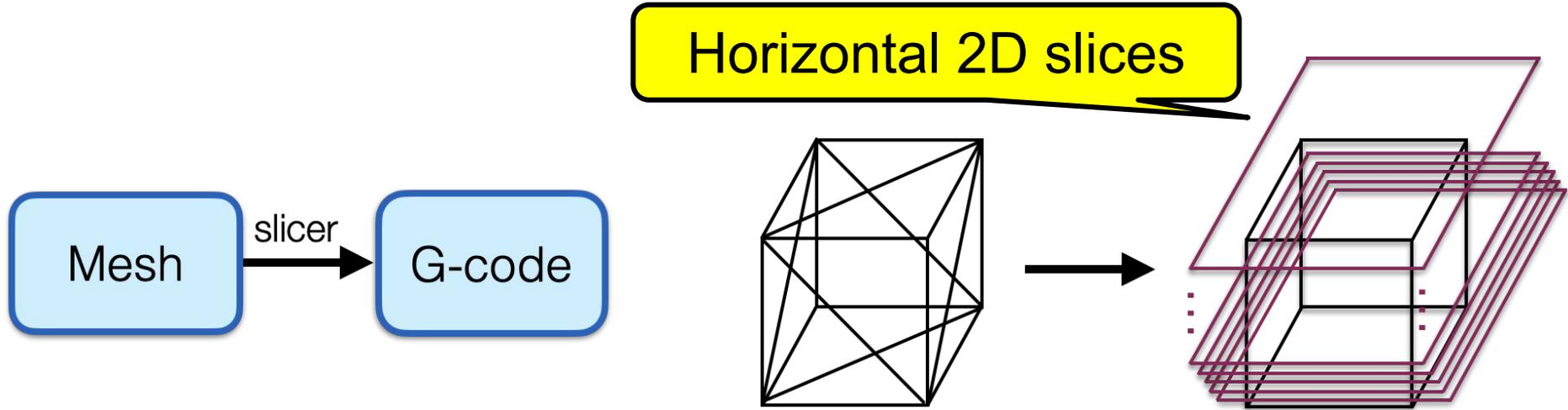
Each component affects the others



# G-code Generator

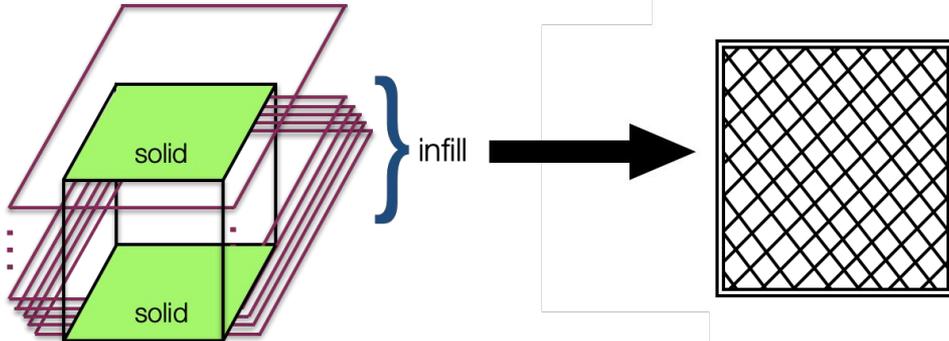
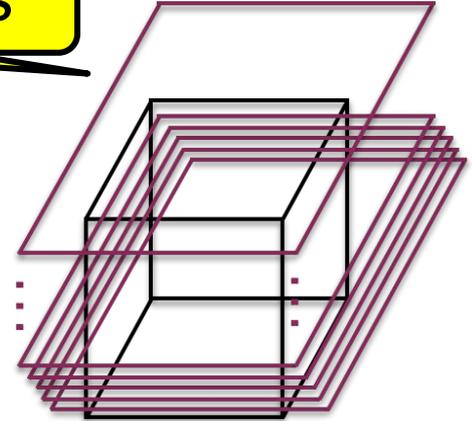
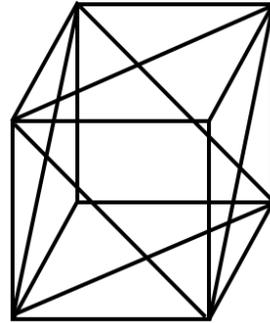
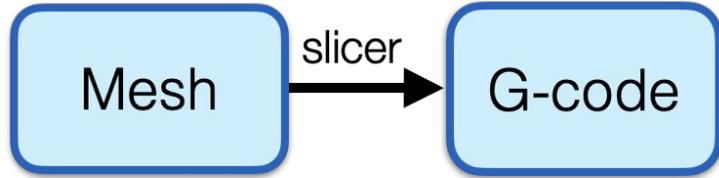


# G-code Generator

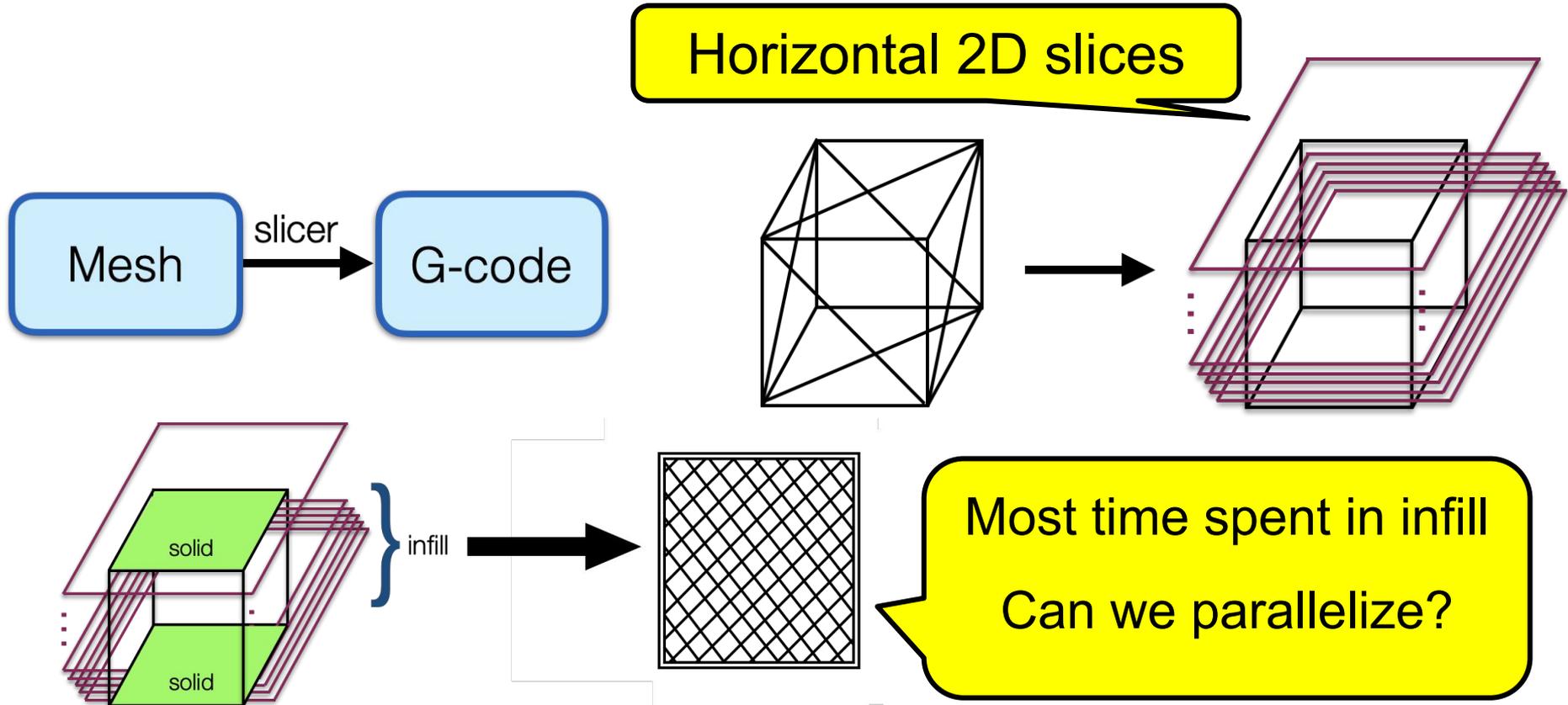


# G-code Generator

Horizontal 2D slices



# G-code Generator



# G-code Generation for Parallel Infill

Printer and design  
agnostic

Works on single model

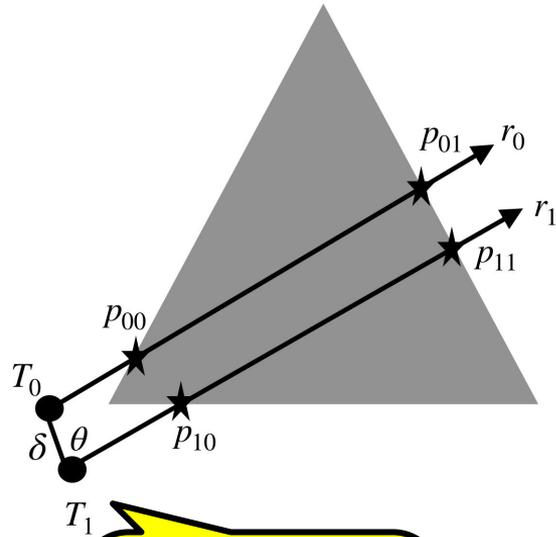
Simulate results

Early prototype  
parameterized by design

Parallelize infill on single  
model

Early simulator prototype

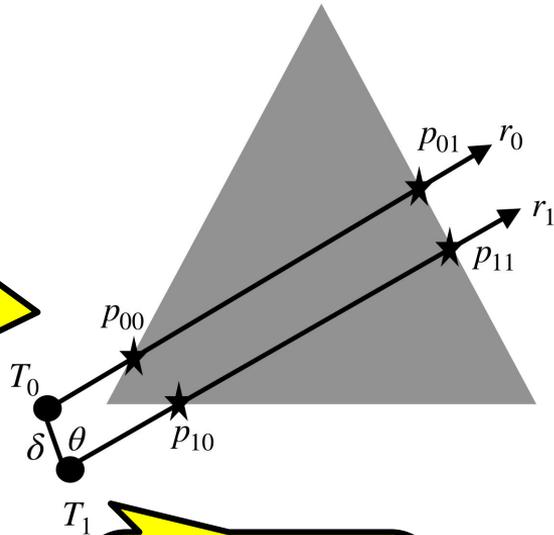
# Early Ideas for G-code Generation for Parallel Infill



$T_0$  and  $T_1$  are  
two extruders  
separated by  $\delta$

# Early Ideas for G-code Generation for Parallel Infill

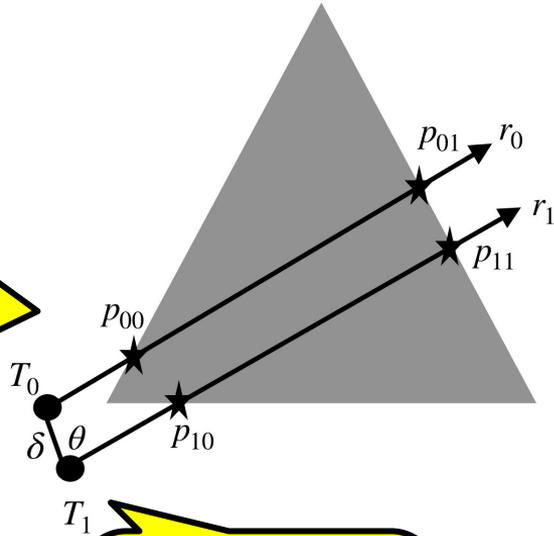
Compute start and stop points for both extruders based on ray intersections with the perimeter



T0 and T1 are two extruders separated by  $\delta$

# Early Ideas for G-code Generation for Parallel Infill

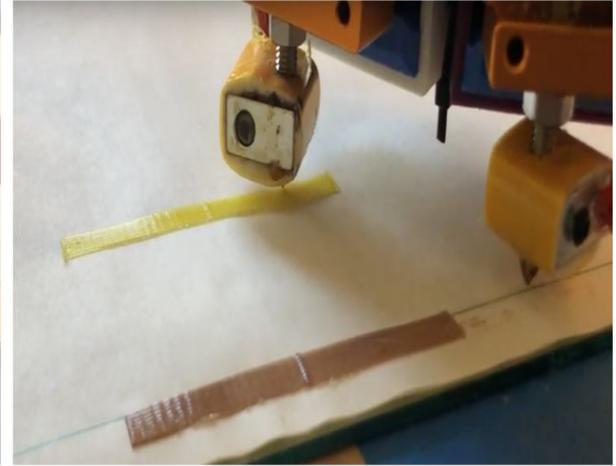
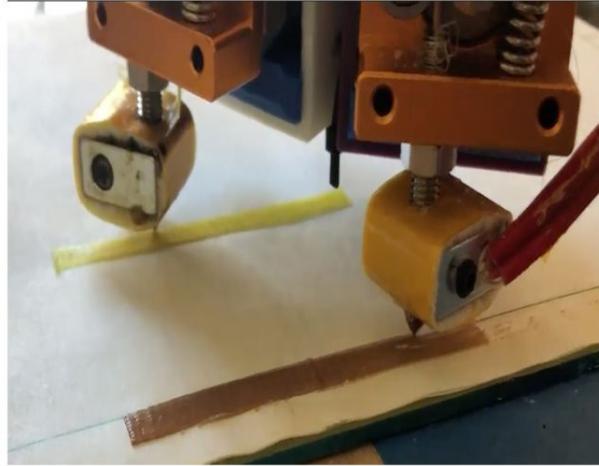
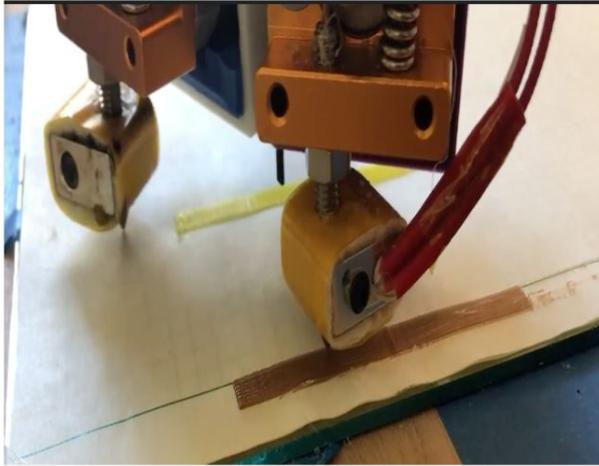
Compute start and stop points for both extruders based on ray intersections with the perimeter



T0 and T1 are two extruders separated by  $\delta$

Generate G-code commands wrapped by `M605 S2` where both extruders should extrude

# Early End-to-End Experiments



Simulated estimates indicate up to 2x speedups possible for basic models

# Going Forward from Our Exploration

Support complex models with multiple islands

Extend to support parallel perimeter

Support different printers

Analyze mesh to detect additional opportunities for parallelism

Analyze CAD to recommend more parallelizable designs

Better simulators for parallel G-code

# A Roadmap Towards Parallel Printing for Desktop 3D Printers

